

# CHAPTER 18 – AIRPLANE GENERAL

## TABLE OF CONTENTS

	Page
TABLE OF CONTENTS   Table of Contents	<b>18-00</b> 18-00-1
INTRODUCTION	<b>18-10</b>
Introduction	18-10-1
FLIGHT MANAGEMENT SYSTEM	<b>18-20</b>
Flight Management System	18-20-1
System Circuit Breakers	18-20-5
GLOBAL POSITIONING SYSTEM	<b>18-25</b>
Global Positioning System	18-25-1
System Circuit Breakers	18-25-3
VHF NAVIGATION	<b>18-30</b>
VHF Navigation	18-30-1
System Circuit Breakers	18-30-8
AUTOMATIC DIRECTION FINDER	<b>18-40</b>
Automatic Direction Finder	18-40-1
System Circuit Breakers	18-40-6
DISTANCE MEASURING EQUIPMENT	<b>18-50</b>
Distance Measuring Equipment	18-50-1
System Circuit Breakers	18-50-6
AIR TRAFFIC CONTROL TRANSPONDER SYSTEM	<b>18-60</b>
Air Traffic Control Transponder System	18-60-1
Mode S Transponder (Flight ID) <0094>	18-60-6
System Circuit Breakers	18-60-8
TRAFFIC ALERT AND COLLISION AVOIDANCE SYSTEM	<b>18-70</b>
Traffic Alert and Collision Avoidance System	18-70-1
Traffic Advisory	18-70-5
Resolution Advisory	18-70-5
Aural Warning	18-70-8
System Circuit Breakers	18-70-10
GROUND PROXIMITY WARNING SYSTEM Ground Proximity Warning System or	<b>18-80</b> 18-80-1

Flight Crew Operating Manual CSP A-013	MASTER

<u>canadaır</u>		Vol. 1	18-00-2
HEGIONAL PAN F	NAVIGATION SYSTEMS Table of Contents	REV	56, Jan 31/03
Enhanced Ground	d Proximity Warning System <0040>		18-80-
Mode 1 - Ex	cessive Descent Rate		18-80-
Mode 2 - Ex	cessive Terrain Closure Rate		18-80-2
Mode 3 – Altitude Loss After Take-off			18-80-3
Mode 4 - Un	safe Terrain Clearance		18-80-3
Mode 5 - Be	low Glideslope Alert		18-80-4
Mode 6 - Ca	llouts		18-80-
Mode 7 - Wi	ndshear Detection and Alerting		18-80-0
System Circu	uit Breakers		18-80-13
WEATHER RADAR S	SYSTEM		18-9
Weather Radar S	vstem		18-90-

Veather Radar System	18-90-1
System Circuit Breakers	18-90-7

## LIST OF ILLUSTRATIONS

FL	IGHT MANAGEMENT S Figure 18-20-1	SYSTEM FMS - Block Diagram	18-2	0-3
	Figure 18-20-2	FMS CDU - Front Panel Layout <0024><0050>	18-2	0-4
GL	OBAL POSITIONING S	SYSTEM		
	Figure 18-25-1	Global Positioning System	18-2	5-2
	Figure 18-25-2	Multifunction Display (2) Pilot's and Copilot's Instrument Panels	18-2	5-3
VH	F NAVIGATION			
	Figure 18-30-1	VHF Navigation System - Block Diagram	18-3	0-2
	Figure 18-30-2	VHF Navigation - Radio Tuning Unit	18-3	0-3
	Figure 18-30-3	VHF Navigation	18-3	0-4
	Figure 18-30-4	VHF Navigation - Bearing Source	18-3	0-5
	Figure 18-30-5	VHF Navigation - Deviation/Source Indicator	18-3	0-6
	Figure 18-30-6	VHF Navigation Vertical Deviation Flag	18-3	0-7
AU	TOMATIC DIRECTION	FINDER	10 /	0.2
	Figure 10-40-1	Automatic Direction Finder ADE Kov	10-4	0-2
	Figure 18-40-2	Automatic Direction Finder ADF Key	18-4	0-3
	Figure 18-40-3	Automatic Direction Finder	18-4	0-4
	Figure 18-40-4	Automatic Direction Finder – Bearing Source	18-4	0-5
DIS	STANCE MEASURING	EQUIPMENT		
	Figure 18-50-1	Distance Measuring Equipment System Interfa	ce 18-5	0-2
	Figure 18-50-2	Distance Measuring Equipment Radio Tuning	Unit 18-5	0-3
		Flight Crew Operating Manual	MASTER	
		CSP A-013		

	NAVIGATION SYSTEMS	Vol. 1	18-00-3
1ªS	Table of Contents	REV	56, Jan 31/03
Figure 18-50-3	Distance Measuring Equipment – Audio Control Panel and Indications		18-50-4
Figure 18-50-4	Distance Measuring Equipment - Multifunc	tion Dis	splay 18-50-5
Figure 18-60-1	Air Traffic Control Transponder System - C	ontrols	18-60-1
Figure 18-60-2	Air Traffic Control Transponder System - Radio Tuning Unit		18-60-2
Figure 18-60-3	ATC Transponder Interface		18-60-3
Figure 18-60-4	Radio Tuning Unit - Top Level Page		18-60-4
Figure 18-60-5	Air Traffic Control Transponder System - Radio Tuning Unit - ATC Main Page		18-60-4
Figure 18-60-7	Flight Identification - RTU		18-60-7
Figure 18-60-9	Flight Identification -FMS		18-60-9
TRAFFIC ALERT AN Figure 18-70-1	ID COLLISION AVOIDANCE SYSTEM Traffic Collision Avoidance System – Threat Level and Data Tags		18-70-1
Figure 18-70-2	Traffic Collision Avoidance System Interface		18-70-2
Figure 18-70-3	Traffic Collision Avoidance System – Controls		18-70-3
Figure 18-70-4	Traffic Collision Avoidance System - Radio Tuning Unit		18-70-4
Figure 18-70-5	Traffic Collision Avoidance System - PFD I	ndicatio	ons 18-70-6
Figure 18-70-6	Traffic Alert and Collision Avoidance Syster MFD Indications	n -	18-70-7
Figure 18-80-1	Ground Proximity Warning System		10 00 7
Figuro 19, 90, 2	Ground Provimity Warning System Control	ale	10-00-7
Figure 18-80-2	Ground Proximity Warning System - Contro Ground Provimity Warning System -	15	10-00-0
Figure 18-80-5	Windshear Detection and Alerting		18-80-9
Figure 18-80-	Ground Proximity Warning System Status Page		18-80-12
Figure 18-90-1	Weather Radar System		18-90-2
Figure 18-90-2	Weather Radar System Control Panel		18-90-3
Figure 18-90-3	Weather Radar System - MFD Indications		18-90-4
Figure 18-90-4	Weather Radar System - MFD Indications		18-90-6

Flight Crew Operating Manual CSP A-013	MASTER



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Flight Crew Operating Manual CSP A-013	MASTER

### 1. INTRODUCTION

The aircraft is equipped with the following navigation systems:

- Flight Management System (FMS)
- VHF Navigation
- Automatic Direction Finder (ADF)
- Distance Measuring Equipment (DME)
- Air Traffic Control (ATC) Transponder System
- Traffic Alert and Collision Avoidance System (TCAS)
- Ground Proximity Warning System (GPWS)
- Enhanced Ground Proximity Warning System (EGPWS) <0040>
- Weather Radar System

Two separate VHF systems are provided for radio navigation and are designed and installed so that the failure of one system does not prevent the operation of the other. Both systems are connected to the onside and cross-side flight compartment displays and controls.

The navigation receivers are tuned by two radio tuning units and navigation data is displayed on the primary flight displays (PFD's) and multifunctional displays (MFD's).

Frequency selection is accomplished through the two radio tuning units. In the event of a failure of one or both radio tuning units, radio communication and navigation can be controlled by the backup tuning unit.

Display control panels permit control over the multifunctional display formats, navigation source and bearing source display.

Audio monitoring is provided by three audio control panels.

Flight Crew Operating Manual CSP A-013	MASTER



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Flight Crew Operating Manual	MASTER
C3P A-013	



## 1. FLIGHT MANAGEMENT SYSTEM

The flight management system (FMS) is an integrated navigation system that provides worldwide point-to-point and great circle navigation. The FMS can be used for:

- NAV Sensor Control (VOR/DME, AHRS)
- NAV Sensor Control (VOR/DME, AHRS and GPS) <0027><0047>
- NAV Sensor Control (VOR/DME, IRS and GPS) <0025><0027><0047>
- NAV Sensor Control (VOR/DME, and IRS) <0025>
- Dead Reckoning (DR)
- N1 Thrust Settings and Computation
- Secondary Radio Tuning
- MFD Control Menus
- Lateral Flight Plan Point-to-Point Navigation
- Flight Parameter Computations
- Fuel and Time Predictions
- Lateral Steering Command Outputs (flight control systems)
- Vertical Steering advisories
- Non-precision approaches

The FMS consists of a flight management computer, located in the avionics compartment, and a control display unit located in the center console. The flight management computer collects information from the navigation sensors and performs all computations, control and command functions. The control display unit provides the pilot interface for data input and control functions, and provides display of functions, modes and flight data. Pictorial data is displayed on the multifunctional displays. <0050>

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A portable data loader is used to transfer data to and from the FMS and maintenance diagnostic computer (MDC).

Flight Crew Operating Manual CSP A-013	MASTER



A data loader, installed on the forward bulkhead behind the galley, is used to transfer data to and from the FMS and maintenance diagnostic computer (MDC). <0018>

The system uses all available sensors and provides the pilot with control of which sensors are used in the position computation. If no sensor data is available, the system continues to estimate a dead reckoning position using heading and true airspeed.

### NOTE

For complete FMS operating instructions, refer to the FMS-4200 Pilot's Guide

Elight Crow Operating Manual	MASTED
CSP A-013	IVIASTER

NAVIGATION SYSTEMS	Vol. 1	18-20-3
Flight Management System	REV	56, Jan 31/03



FMS – Block Diagram <MST> Figure 18-20-1

	Flight Crew Operating Manual CSP A-013	MASTER
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FMS CDU – Front Panel Layout <0024><0050> Figure 18-20-2

Flight Crew Operating Manual CSP A-013	MASTER	



**Vol. 1** 18-20-5

REV 56, Jan 31/03

## A. System Circuit Breakers

SYSTEM	SUB-SYSTEM	CB NAME	BUS BAR	CB PANEL	CB LOCATION	NOTES
Flight Management Control System Display Unit (FMS)	CDU 1	DC BUS 1	1	H12		
	Display Unit	CDU 2	DC BUS 2	2	H12	<0024>

Flight Crew Operating Manual CSP A-013	MASTER



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Flight Crew Operating Manual CSP A-013	MASTER



Vol. 1 18-25-1

### 1. <u>GLOBAL POSITIONING SYSTEM</u> <0027><0047>

The Global Positioning System (GPS) is a satellite navigation system that computes the position of the aircraft relative to orbiting satellites. The GPS provides highly accurate three-dimensional position, velocity and time information to the integrated avionics processor system (IAPS). The FMS control display units provides the pilots with access to GPS data and control settings. GPS information is displayed on the multifunctional displays.

The GPS consists of a receiver and antenna. The antenna supplies signals to the receiver which processes the signals and supplies continuous navigation updates to the attitude heading reference system (AHRS) and to the flight management system (FMS) The FMS uses the GPS and other available navigation and position sensors to provide navigation, position information and guidance.<0047>

The GPS consists of a receiver and antenna. The antenna supplies signals to the receiver which processes the signals and supplies continuous navigation updates to the inertial reference system (IRS) and to the flight management system (FMS) The FMS uses the GPS and other available navigation and position sensors to provide navigation, position information and guidance.<0025><0047>

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The GPS employs 24 satellites, with each satellite transmitting time and orbital position signals. The receiver decodes the signals and computes time, range, and position of the aircraft and other navigation parameters. The GPS satellites are controlled by a master control station in Colorado Springs, Colorado, USA. The receiver is a fifteen-channel unit that is capable of tracking up to twelve satellites but must track at least four satellites to measure the corresponding ranges.

The FMS control display unit provides the pilots with access to GPS data and control settings. GPS information is displayed on the multifunctional displays.

#### NOTE

Refer to the FMS-4200 Pilot's Guide for further information.

Flight Crew Operating Manual CSP A-013	MASTER





Global Positioning System <MST> Figure 18-25-1

Flight Crew Operating Manual MASTER CSP A-013
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Multifunction Display (2) Pilot's and Copilot's Instrument Panels <MST> Figure 18-25-2

Flight Crew Operating Manual CSP A-013	MASTER



## A. System Circuit Breakers

SYSTEM	SUB-SYSTEM	CB NAME	BUS BAR	CB PANEL	CB LOCATION	NOTES
Global Positioning	Pocoivor	GPS 1	DC BUS 1	1	G11	<0047>
System	Receiver	GPS 2	DC BUS 2	3	H13	<0027>



### 1. VHF NAVIGATION

There are two VHF navigation systems installed on the aircraft. The systems are identified as VHF/NAV 1 and VHF/NAV 2. The systems provide the following functions:

- VHF omnidirectional range (VOR)
- Localizer/glideslope (LOC/GS)
- Marker beacon (MB).

Frequency tuning and mode selection can be done by two radio tuning units, a single backup tuning unit or by the FMS control display unit. The radio tuning units (RTU's) are the primary radio communication system radio tuning source. (Refer to Chapter 5, Communications, for information on the radios and backup tuning unit).

The VOR/LOC receivers operate in the following frequency ranges:

- VOR frequencies All even frequencies from 108.00 to 111.90 MHz and all frequencies from 112.00 to 117.95
- LOC frequencies All odd frequencies from 108.10 to 111.95 MHz.

The NAV receivers monitor the selected VOR stations and provide enroute and terminal area navigation. The VOR data is displayed on the pilots and copilots PFD and MFD.

In LOC and GS modes, the NAV receivers supply final approach guidance data. Localizer signals are monitored for horizontal deviation and glideslope signals are monitored for vertical deviation. When the navigation receiver is tuned to a localizer frequency, the paired glideslope frequency is automatically tuned. The LOC/GS data is displayed on the pilots and copilots PFD and MFD.

The Marker Beacon (MB) system provides information on distance to the runway. The MB antennas receive signals from the outer, middle and inner MB ground transmitters. The signals are then supplied to the receivers. MB information is displayed on the pilots and copilots PFD. MB sensitivity can be adjusted at the radio tuning units.

The VHF/NAV system also supplies VOR/LOC and MB station identification to the audio integrating system.

Flight Crew Operating Manual CSP A-013	MASTER













### NAVIGATION SYSTEMS VHF Navigation

REV 56, Jan 31/03

MASTER



Flight Crew Operating Manual

CSP A-013





Flight Crew Operating Manual MASTER CSP A-013





Primary Flight Display Pilot's and Copilot's Instrument Panels

VHF Navigation Vertical Deviation Flag <MST> Figure 18-30-6

	Flight Crew Operating Manual CSP A-013	MASTER
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## A. System Circuit Breakers

SYSTEM	SUB-SYSTEM	CB NAME	BUS BAR	CB PANEL	CB LOCATION	NOTES
VHF	Pocoivors	VHF NAV 1	DC ESS	4	D6	
Navigation	Receivers	VHF NAV 2	DC BUS 2	2	H9	

Flight Crew Operating Manual CSP A-013	MASTER



### 1. AUTOMATIC DIRECTION FINDER

The automatic direction finder (ADF) system is a dual, low frequency radio system designated as ADF 1 and ADF 2. The ADF system is used to indicate relative bearing from the aircraft to a selected ground station.

The transmitting stations can be non-directional beacons (NDBs) or standard amplitude modulation (AM) broadcast stations in the frequency range of 190.0 to 1799.0 Khz. The receivers operate in the following modes:

- Antenna (ANT) mode Functions as an aural receiver
- ADF mode Functions as a direction finder indicating bearing to station and outputs an aural tone
- Tone mode Allows identification of keyed continuous wave (CW) signals by using a 1000-Hz aural output circuit.

Frequency tuning and ADF mode selections is made through the radio tuning units. Station audio is controlled through the audio control panels.

Frequency tuning can also be made on the FMS control display unit. <0024><0050>

### NOTE

When the microphone is keyed during HF transmissions, the ADF pointers will freeze.

Bearing selection is made on the pilot and copilot display control panels and the bearing-to-station data is displayed on the HSI portion of the pilots and copilots primary flight display (PFD) and on the multifunctional display (MFD), in HSI, navaid sector and present position map formats.

Flight Crew Operating Manual CSP A-013	MASTER



Automatic Direction Finder System Interface <MST> Figure 18-40-1

CSP A-013
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#### Radio Tuning Unit - ADF Main Page Center Pedestal

Automatic Direction Finder ADF Key <MST> Figure 18-40-2

	Flight Crew Operating Manual CSP A-013	MASTER
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Selected setting is displayed in cyan.





Display Control Panel Pilot's and Copilot's Side Panels

Automatic Direction Finder <MST> Figure 18-40-3

Flight Crew Operating Manual MASTER CSP A-013
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## NAVIGATION SYSTEMS Automatic Direction Finder

**Vol. 1** 18-40-5

REV 56, Jan 31/03



Flight Crew Operating Manual CSP A-013	MASTER
CSP A-013	



## A. System Circuit Breakers

SYSTEM	SUB-SYSTEM	CB NAME	BUS BAR	CB PANEL	CB LOCATION	NOTES
Automatic Direction	Pocoivor	ADF 1	DC ESS	4	D4	
Finder	ADF 2	DC BUS 2	2	H7		

Flight Crew Operating Manual MASTER CSP A-013
--



### 1. DISTANCE MEASURING EQUIPMENT

There are two identical distance measuring equipment (DME) systems installed in the aircraft. The DME system computes and displays the straight line distance between the aircraft and a selected DME ground station. The DME system also provides ground speed, time to station and station identification.

There are two DME transceivers installed in the avionics compartment that operate in the frequency range of 962 to 1213 MHz with a range of 300 nautical miles at 30,000 feet. Each transceiver has three channels and can track up to three stations simultaneously. Channel 1 of each DME is paired with the onside VOR and can be manually tuned by either the radio tuning units, or backup tuning unit.

The DME transceiver is also tuned automatically by the FMS through the RTU. If Autotune is selected on the control display unit, the FMS will automatically tune VOR/DME channel 1.  $_{<0024><0050>}$ 

The DME transceivers interrogate the ground station at regular intervals. The ground station sends replies with a signal that is above or below the airborne DME frequency by 63 MHz. When a reply is received by the DME, it measures the elapsed time between the transmitted signal and the reply, then computes the slant distance, ground speed and time-to-go to the ground station.

The DME hold function splits the paired tuning between DME and VHF navigation systems to enable independent operation. The DME hold function holds the DME transceiver to the current VHF navigation frequency and permits the VHF navigation receiver to be independently tuned. The DME frequency can also be tuned independently while the VHF navigation receiver is kept at the current frequency.

Frequency tuning and DME hold selections are through the radio tuning units. The DME frequency channels are paired with the VHF navigation channels. The frequency selection is done with the pilot's or copilot's RTUs in the frequency range of 108.00 to 117.95 MHz. Station audio is monitored through the audio control panels. Visual indications of tuned stations, distance readouts and DME hold indications are provided on the primary flight displays and multifunctional displays.

Flight Crew Operating Manual CSP A-013	MASTER



Distance Measuring Equipment System Interface <MST> Figure 18-50-1

Flight Crew Operating Manual CSP A-013	MASTER



### NAVIGATION SYSTEMS Distance Measuring Equipment

**Vol. 1** 18-50-3

REV 56, Jan 31/03



Center Pedestal

Distance Measuring Equipment Radio Tuning Unit <MST> Figure 18-50-2

Flight Crew Operating Manual CSP A-013	MASTER
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Flight Crew Operating Manual CSP A-013

MASTER





Pilot's and Copilot's Instrument Panels

Distance Measuring Equipment – Multifunction Display Figure 18–50–4

Flight Crew Operating Manual CSP A-013	MASTER
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## A. System Circuit Breakers

SYSTEM	SUB-SYSTEM	CB NAME	BUS BAR	CB PANEL	CB LOCATION	NOTES
Distance Measuring Equipment	Transceiver	DME 1	DC BUS 1	1	H10	
		DME 2	DC BUS 2	2	H10	


## 1. AIR TRAFFIC CONTROL TRANSPONDER SYSTEM

The two air traffic control transponders (ATC 1 and ATC 2) provide ground radar beacon systems with coded identification responses in the following modes:

- Mode A Aircraft identify reporting
- Mode C Altitude reporting
- Mode Select (S) Data link with other mode S transponders for the traffic alert and collision avoidance system (TCAS).

Mode S data link includes air-to-air, ground-to-air (data uplink or comm A), air-to-ground (data downlink or comm B), and multisite (ground station to ground station) messages. The transponder code range is from 0000 to 7777, selectable through the RTU's.



Center Pedestal

Air Traffic Control Transponder System – Controls <MST> Figure 18-60-1

Transponder codes are set on the top level page of the radio tuning units and can also be set using the FMS control display unit. ATC identification is selected using the IDENT button on the RTU.

Altitude reporting selection is made on the ATC main page of the radio tuning unit.



134.920 <0012> <0012>123.450 Tuning Window (white) IDENT R Pushed at ATC request; causes an IDENT COM1 ACT PRE 🖛 additional identification pattern on ATC  $\left[ \right]$ 123.45 0 134.92 ground radar screen. SQ OFF TX DME-H NAV1 ACT PRE  $\bigcirc$ 0 110.15 AUT 118.15 Transponder Code (green) 1/2 MK-HI Turns white when selected to standby. O) 0 ADF1 TCAS ATC Key 224.0 AUTO REL Push key once to tune frequency 0  $\left[ \circ \right]$ ACT1 with tuning knob. Push key twice to 2345 select ATC main page. STBY  $\overline{m}$ Mode Messages (cyan)  $\mathbb{A}$ • STBY - Both transponders are in standby mode. Code turns white. • ALT OFF - Mode C selected off. • ID - Identification has been selected. • R - Transponder is responding to an Radio Tuning Unit - Top Level Page interrogation. Center Pedestal **TUNING KNOB** 

> Air Traffic Control Transponder System – Radio Tuning Unit <MST> Figure 18-60-2

Flight Crew Operating Manual CSP A-013	MASTER



## NAVIGATION SYSTEMS Air Traffic Control Transponder System

**Vol. 1** 18-60-3

REV 56, Jan 31/03



ATC Transponder Interface <MST> Figure 18-60-3

	Flight Crew Operating Manual CSP A-013	MASTER
--	---	--------



REV 56, Jan 31/03





# 2. MODE S TRANSPONDER (FLIGHT ID) <0094>

Mode S also has the capability to display either a 4-digit squawk code or the flight identification (FLT ID) on line 4 of the RTU Top Level Page. Selection of either the squawk code or the FLT ID for display on the Top Level Page is made on the ATC Main Page.

To access the ATC Main Page from the Top Level Page, the ATC Line Select Key is pressed twice. Once the Main Page is displayed, the DISPLAY Line Select Key is pressed to select either the SQUAWK or FLT ID (the selected function will be displayed larger). The selected function is then displayed on line 3 of the Main Page, line 4 of the Top Level Page and on the FLT ID Page. To modify the squawk code or the FLT ID on the Top Level Page, the ATC Line Select Key is pressed, which will cause a tune window to surround the left character. The small Tuning Knob is then used to change the character displayed in the tune window. The RTU then waits 2 seconds after knob rotation stops before locking in the new character. Rotating the large tune knob cycles the tune window from character to character.

To access the FLIGHT ID Main Page from the ATC Main Page, the FLT ID key is pressed twice. On the FLIGHT ID Main Page, the RTU displays an Active and Preset Flight ID. By pressing the top right line-select key the ACTIVE and Preset FLT ID will swap when the tune window is on a Preset Flight ID character.

The FMS can also display the FLIGHT ID on the "RADIO TUNING PAGE" page 2 of 2, adjacent to the top right line select key on the CDU. To input the FLIGHT ID data:

- Press the top right line select key on the CDU so that the selection box highlights the FLIGHT ID information field.
- Input the FLT ID data, via the CDU keypad, where it will appear on the bottom left corner of the page (in brackets).
- After the FLT ID has been inputted, press the top right line select key and check that the proper FLT ID appears adjacent to the top right line select key.

Flight Crew Operating Manual CSP A-013	MASTER



0  $\mathbb{O}$ ACT COM1 PRE 🗕 **IDEN** 123.45 SQ OFF TX ACT NAV1 0 <0012> 123.450  $\bigcirc$ 134.92 134.920 <0012> NAV1 AUT <0024><0050> PRE  $\bigcirc$  $\bigcirc$ 110.15 мк-ні 118.15  $\bigcirc$  $\bigcirc$ ADF1 TCAS 224.0 AUTO REL 0  $\bigcirc$ ATC 1 4567 ATC LINE  $\mathbb{D}$ SELECT KEY Radio Tuning Unit - Top Level Page 0 IDENT ATC 1  $\bigcirc$ 4567 0 חו ALT ON OFF  $\left[ \right]$ 0 FLT ID KEY. **DISPLAY TIME** SELECT KEY  $\bigcirc$ þ FLT ID <0094> N 96BP  $\bigcirc$ 0 DISPLAY SQWK FLT ID <0094> RETURN Radio Tuning Unit - ATC Main Page TUNING KNOB 0  $(\mathbb{D})$  $\mathbb{D}$ ATC 1 PRE 🕶 IDENT ACT 0 <0094> N96BP123  $\bigcirc$ FID///// <0094>  $\bigcirc$ Q  $\bigcirc$ 0  $\bigcirc$ RETURN

Radio Tuning Unit - Flight ID Main Page

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Flight Identification – RTU <MST> Figure 18–60–6

	Flight Crew Operating Manual CSP A-013	MASTER	
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## NAVIGATION SYSTEMS Air Traffic Control Transponder System

Vol. 1 18-60-7

REV 56, Jan 31/03





# NAVIGATION SYSTEMS Air Traffic Control Transponder System

Vol. 1 18-60-8

REV 56, Jan 31/03



Flight Crew Operating Manual CSP A-013	MASTER	



**Vol. 1** 18-60-9

REV 56, Jan 31/03

# A. System Circuit Breakers

SYSTEM	SUB-SYSTEM	CB NAME	BUS BAR	CB PANEL	CB LOCATION	NOTES
Air Traffic	Transpondor	XPDR 1	DC ESS	4	D5	
Control	Transponder	XPDR 2	DC BUS 2	2	H8	

Flight Crew Operating Manual CSP A-013	MASTER
	1



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Flight Crew Operating Manual	MASTER
C3P A-013	



### 1. TRAFFIC ALERT AND COLLISION AVOIDANCE SYSTEM

The traffic alert and collision avoidance system (TCAS) is an airborne system that interrogates the air traffic control transponders of nearby aircraft to identify and display potential and predicted collision threats. TCAS surveillance range is up to 40 nautical miles and can detect and track up to 30 aircraft simultaneously. The system computes range, bearing and closure rates of other transponder equipped aircraft.

A mode "S" Transponder provides air-to-air communications for coordinating the resolution maneuvers between TCAS equipped aircraft. The TCAS system provides no indication of traffic conflicts if the intruder aircraft is without an operative transponder.

TCAS provides symbology that depicts surrounding aircraft in terms of relative altitude, range, clock position, and vertical rate. The flight compartment displays also provide data on closure rates. The system displays four types of traffic.

The display control panels are used to activate TCAS and to set range display. Weather radar data can be overlaid on the multifunctional display, in TCAS mode.

TCAS mode and altitude format are displayed on the top level page of the radio tuning units. Testing and setting changes are made on the TCAS main page.

SYMBOL	COLOR	THREAT LEVEL	THREAT LEVEL DEFINITION	CAUSE
+01 ↓	RED	Resolution Advisory (RA)	Intruding aircraft 25 seconds from closest point of approach	Intruding aircraft is above by 100 feet and descending at least 500 feet per minute
+00	AMBER	Traffic Advisory (TA)	Intruding aircraft 40 seconds from closest point of approach	Intruding aircraft level with and not climbing or descending
-12	CYAN	Proximate Traffic	Any traffic within surveillance range and ±1,200 feet vertical	Traffic below 1,200 feet and climbing at least 500 feet per minute
+27	CYAN	Other Traffic	Any traffic within TCAS range limit	Traffic above 2,700 feet and descending at least 500 feet per minute

#### TCAS DISPLAY THREAT LEVELS AND DATA TAGS

Traffic Collision Avoidance System – Threat Level and Data Tags Figure 18-70-1

Flight Crew Operating Manual CSP A-013	MASTER





Traffic Collision Avoidance System Interface <MST> Figure 18-70-2

Flight Crew Operating Manual CSP A-013	MASTER



REV 56, Jan 31/03



**Display Control Panel** Pilot's and Copilot's Side Panels Used to directly select TCAS traffic display on MFD.

 $\begin{array}{l} \mbox{Traffic Collision Avoidance System - Controls < MST > } \\ \mbox{Figure 18-70-3} \end{array}$ 

Flight Crew Operating Manual CSP A-013	MASTER





Radio Tuning Unit - Top Level Page Center Pedestal

#### **Mode Selection**

Used to select TCAS mode. Selected mode is displayed in cyan.

- AUTO All advisories are displayed.
- STBY All interrogations are inhibited.
- TA ONLY Only traffic advisories are displayed.



Used to select altitude format.

REL - Relative to own airplane altitude.

ABS - Absolute with respect to barometric altitude.

Traffic Collision Avoidance System - Radio Tuning Unit <MST> Figure 18-70-4

	Flight Crew Operating Manual CSP A-013	MASTER	



### A. Traffic Advisory

The traffic advisory (TA) is issued to indicate the relative positions of intruding aircraft that are about 40 seconds from the closest point of approach.

Traffic advisories are displayed on the MFD (in TCAS mode) and shows the relative position of nearby ATC transponder equipped aircraft.

The traffic advisory allows the flight crew an opportunity to visually locate the intruding aircraft. The advisory is always displayed on the PFDs or can be displayed on the TCAS page of the MFD if selected from the display control panel.

TA ONLY (Traffic advisory only) will be displayed automatically when the aircraft is 1000 feet or below, and will revert to pre-selected mode automatically when the aircraft is above 1000 feet.

#### B. Resolution Advisory

Resolution advisories (RA) will direct the flight crew to resolve a threat by executing an aircraft maneuver that will increase separation. This occurs when the TCAS computer predicts that the intruding aircraft is within about 25 seconds from the closest point of approach.

Resolution advisories are displayed on the vertical speed indicator (VSI) portion of the PFD. The VSI shows the appropriate vertical maneuver to avoid the threat. The VSI provides vertical guidance to maintain safe vertical separation as follows:

- Corrective RAs Fly from the red zone to the green zone
- Preventive RAs Do not fly into the red zone.

The vertical maneuver is also accompanied by TCAS voice warnings.

#### NOTE

The TCAS resolution advisory programs are based on the pilot initiating the RA maneuver within approximately 5 seconds. If an additional corrective resolution advisory is issued (e.g. a reversal), the maneuver must be initiated within 2.5 seconds.

Flight Crew Operating Manual CSP A-013	MASTER
C3F A-013	





Traffic Collision Avoidance System – PFD Indications <MST> Figure 18-70-5

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REV 56, Jan 31/03



**RADAR NOT AT TCAS RANGE (cyan)** Weather radar control has been transferred and range disagrees with TCAS range.

#### NOTES

- 1. Weather radar can be displayed on the MFD when in TCAS mode (range: 5,10, 20 and 40 nm).
- 2. TCAS can be overlaid on any map display mode.
- 3. During an electrical transient, TCAS display range may default to 10 nm.

Traffic Alert and Collision Avoidance System – MFD Indications Figure 18–70–6

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# C. Aural Warning

The system provides appropriate aural warnings to the flight crew when the TCAS computer analysis of an aircraft signal predicts a penetration of TCAS protected airspace. The voice warnings cannot be cancelled or reduced in volume.

TA voice warning is TRAFFIC - TRAFFIC

RA voice warnings are:

- CLIMB, CLIMB, CLIMB
- DESCEND, DESCEND, DESCEND
- MONITOR VERTICAL SPEED, MONITOR VERTICAL SPEED
- CLIMB CROSSING CLIMB, CLIMB CROSSING CLIMB
- DESCEND CROSSING DESCEND, DESCEND CROSSING DESCEND
- INCREASE CLIMB, INCREASE CLIMB
- INCREASE DESCENT, INCREASE DESCENT
- CLIMB CLIMB NOW, CLIMB CLIMB NOW
- DESCEND DESCEND NOW, DESCEND DESCEND NOW
- REDUCE CLIMB, REDUCE CLIMB
- REDUCE DESCENT, REDUCE DESCENT

RA voice warnings are:<0042>

- CLIMB, CLIMB, CLIMB
- DESCEND, DESCEND
- MONITOR VERTICAL SPEED
- CLIMB CROSSING CLIMB, CLIMB CROSSING CLIMB
- DESCEND CROSSING DESCEND, DESCEND CROSSING DESCEND
- INCREASE CLIMB, INCREASE CLIMB
- INCREASE DESCENT, INCREASE DESCENT
- CLIMB CLIMB NOW, CLIMB CLIMB NOW
- DESCEND DESCEND NOW, DESCEND DESCEND NOW

Flight Crew Operating Manual CSP A-013	MASTER
C31 A-013	



- MAINTAIN VERTICAL SPEED, MAINTAIN
- MAINTAIN VERTICAL SPEED, CROSSING MAINTAIN
- ADJUST VERTICAL SPEED, ADJUST

The clear advisory is "CLEAR OF CONFLICT".

Flight Crew Operating Manual CSP A-013	MASTER



# D. System Circuit Breakers

SYSTEM	SUB-SYSTEM	CB NAME	BUS BAR	CB PANEL	CB LOCATION	NOTES
Traffic Alert and Collision Avoidance System	Transmitter / Receiver	TCAS	AC ESS	3	C1	

Flight Crew Operating Manual MASTER CSP A-013
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## 1. GROUND PROXIMITY WARNING SYSTEM

## 

## 2. ENHANCED GROUND PROXIMITY WARNING SYSTEM <0040>

The ground proximity warning system (GPWS) is used to help prevent accidents caused by unsafe flight maneuvers in proximity of terrain or severe windshear. GPWS provides the flight crew with aural alerts, messages and visual annunciations in the event that the boundaries of the following alerting envelopes are exceeded:

The enhanced ground proximity warning system (EGPWS) is used to help prevent accidents caused by unsafe flight maneuvers in proximity of terrain or severe windshear. EGPWS provides the flight crew with aural alerts, messages and visual annunciations in the event that the boundaries of the following alerting envelopes are exceeded: <0040>

- Mode 1 Excessive descent rate
- Mode 2 Excessive terrain closure rate
- Mode 3 Altitude loss after take-off
- Mode 4 Unsafe terrain clearance
- Mode 5 Below glideslope alert
- Mode 6 Callouts (descent below minimums, altitude callouts and bank angle alert)
- Mode 7 Windshear detection and alerting
- TAAD Terrain / obstacle awareness alerting and display <0040>
- TCF Terrain clearance floor <0040>

Radar information is displayed on the multifunctional displays by pressing the RDR button on the display control panel.

Radar or terrain information is displayed on the multifunctional displays by pressing the RDR / TERR button on the display control panel. <0040>

#### A. Mode 1 - Excessive Descent Rate

Mode 1 alerts are generated when the aircraft has an excessive descent rate close to the terrain. Mode 1 has two boundaries. Penetration of outer boundary activates the flashing GPWS lights and generates a SINKRATE, SINKRATE aural alert. Penetrating the inner boundary activates the flashing GPWS lights and the repeated WHOOP, WHOOP, PULL UP aural, until the inner warning boundary has been exited.

Flight Crew Operating Manual	MASTER
CSP A-013	



Mode 1 is used for the approach phase of flight and is independent of the aircraft configuration. Mode 1 alerts are generated when the aircraft has an excessive descent rate close to the terrain. Mode 1 has two boundaries. Penetration of the outer boundary activates the flashing GND PROX lights and generates a SINKRATE, SINKRATE aural alert. Penetrating the inner boundary activates the flashing PULL UP lights and the repeated WHOOP, WHOOP, PULL UP aural, until the inner warning boundary has been exited. <0040>

#### B. Mode 2 - Excessive Terrain Closure Rate

Mode 2 alerts are generated when the aircraft is closing with terrain at an excessive rate. Mode 2 has two sub-modes referred to as Mode 2A and Mode 2B. Mode 2A is active during climbout, cruise, and initial approach (flaps not in landing configuration and the aircraft is not on glideslope centerline). Penetrating the outer boundary activates the GPWS lights and generates the TERRAIN, TERRAIN aural. Continued penetration of the envelope will activate the GPWS lights and generate a repeated WHOOP, WHOOP PULL UP aural.

Mode 2 alerts are generated when the aircraft is closing with terrain at an excessive rate. Mode 2 has two sub-modes referred to as Mode 2A and Mode 2B. Mode 2A is active during climbout, cruise, and initial approach (flaps not in landing configuration and the aircraft is not on glideslope centerline). Penetrating the outer boundary activates the GND PROX lights and generates the TERRAIN, TERRAIN aural. Continued penetration of the envelope will activate the PULL UP lights and generate a repeated WHOOP, WHOOP PULL UP aural.<

Upon leaving the PULL UP warning area, if terrain clearance continues to decrease, the TERRAIN aural will be generated until terrain clearance stops decreasing. The GPWS lights will remain on until 300 feet of barometric altitude has been achieved, or 45 seconds has elapsed, or the GPWS FLAP OVRD has been selected, or the flaps are in a landing configuration.

Upon leaving the PULL UP warning area, if terrain clearance continues to decrease, the TERRAIN aural will be generated until terrain clearance stops decreasing. The GND PROX lights will remain on until 300 feet of barometric altitude has been achieved, or 45 seconds has elapsed, or the GND PROX FLAP OVRD has been selected, or the flaps are in a landing configuration. <0040>

Mode 2B is activated when flaps are in landing configuration, when making an ILS approach with glideslope and localizer deviation less than 2 dots, and for the first 60 seconds after take-off. Penetration of the Mode 2B boundary with either gear or flaps not in a landing configuration, activates the GPWS lights and generates a TERRAIN, TERRAIN aural. If the aircraft continues to penetrate the boundary the GPWS lights are activated and a WHOOP, WHOOP PULL UP aural is repeated until the warning envelope is exited.

Flight Crew Operating Manual CSP A-013	MASTER

Mode 2B is activated when flaps are in landing configuration, when making an ILS approach with glideslope and localizer deviation less than 2 dots, and for the first 60 seconds after take-off. Penetration of the Mode 2B boundary with either gear or flaps not in a landing configuration, activates the GND PROX lights and generates a TERRAIN, TERRAIN aural. If the aircraft continues to penetrate the boundary the PULL UP lights are activated and a WHOOP, WHOOP PULL UP aural is repeated until the warning envelope is exited. <0040>

If the aircraft penetrates the Mode 2B boundary with both gear and flaps in a landing configuration, the GPWS lights are activated and a TERRAIN aural is repeated until the envelope is exited.

If the aircraft penetrates the Mode 2B boundary with both gear and flaps in a landing configuration, the GND PROX lights are activated and a TERRAIN aural is repeated until the envelope is exited.<0040>

## C. Mode 3 - Altitude Loss After Take-off

Mode 3 provides alerts when the aircraft loses a significant amount of altitude after take-off, or low altitude go-around with gear or flaps not in a landing configuration. The amount of altitude loss permitted before an alert is generated depends on the height of the aircraft above the terrain.

The alert activates the GPWS lights and generates a DON'T SINK, DON'T SINK aural. The DON'T SINK, DON'T SINK aural is only repeated if the altitude loss continues. The GPWS lights will go out once a positive rate of climb is achieved.

The alert activates the GND PROX lights and generates a DON'T SINK, DON'T SINK aural. The DON'T SINK, DON'T SINK aural is only repeated if the altitude loss continues. The GND PROX lights will go out once a positive rate of climb is achieved. <0040>

## D. Mode 4 - Unsafe Terrain Clearance

Mode 4 provides alerts for insufficient terrain clearance with respect to phase of flight, configuration and speed. Mode 4 has three sub-modes referred to as Mode 4A, Mode 4B and Mode 4C.

Mode 4A is active during cruise and approach with the gear and flaps not in the landing configuration. The boundary for Mode 4A is 500 feet radio altitude and increases linearly with airspeed, to a maximum of 1000 feet radio altitude. If the envelope is penetrated at less than 190 knots, the GPWS lights flash and the TOO LOW GEAR aural alert is generated. If the envelope is penetrated at more than 190 knots, the GPWS lights flash and a TOO LOW TERRAIN aural alert is generated.

Mode 4A is active during cruise and approach with the gear and flaps not in the landing configuration. The boundary for Mode 4A is 500 feet radio altitude and increases linearly with airspeed, to a maximum of 1000 feet radio altitude. If the envelope is penetrated at less than 190 knots, the GND PROX lights flash and the TOO LOW GEAR aural alert is generated. If the envelope is penetrated at more than 190 knots, the GND PROX lights flash and the TOO LOW GEAR aural alert is generated. If the envelope is penetrated at more than 190 knots, the GND PROX lights flash and a TOO LOW TERRAIN aural alert is generated. <0040>

Flight Crew Operating Manual CSP A-013	MASTER	



Mode 4B is active during cruise and approach, with gear down and flaps not in the landing configuration. The boundary for Mode 4B is 245 feet radio altitude and increases linearly with airspeed, to a maximum of 1000 feet radio altitude. If the envelope is penetrated at less than 159 knots, the GPWS lights flash and the TOO LOW FLAPS aural is generated. The flight crew may override the TOO LOW FLAPS alert by selecting the GPWS FLAP OVRD. If the envelope is penetrated at more than 159 knots, the GND PROX lights flash and the TOO LOW TERRAIN aural alert is generated.

Mode 4B is active during cruise and approach, with gear down and flaps not in the landing configuration. The boundary for Mode 4B is 245 feet radio altitude and increases linearly with airspeed, to a maximum of 1000 feet radio altitude. If the envelope is penetrated at less than 159 knots, the GND PROX lights flash and the TOO LOW FLAPS aural is generated. The flight crew may override the TOO LOW FLAPS alert by selecting the GND PROX FLAP OVRD. If the envelope is penetrated at more than 159 knots, the GND PROX lights flash and the TOO LOW TERRAIN aural alert is generated. <0040>

Mode 4C is active during the take-off phase with either gear or flaps not in the landing configuration. Mode 4C alerts the pilot when the terrain is rising more steeply than the aircraft is climbing. Mode 4C is based upon a minimum terrain clearance floor, that increases with radio altitude. If the aircraft radio altitude decreases to the value of the minimum terrain clearance floor, the GPWS lights flash and the TOO LOW TERRAIN aural is generated.

Mode 4C is active during the take-off phase with either gear or flaps not in the landing configuration. Mode 4C alerts the pilot when the terrain is rising more steeply than the aircraft is climbing. Mode 4C is based upon a minimum terrain clearance floor, that increases with radio altitude. If the aircraft radio altitude decreases to the value of the minimum terrain clearance floor, the GND PROX lights flash and the TOO LOW TERRAIN aural is generated. <0040>

The GPWS lights will continue to flash until the alert envelope is exited. Subsequent alerts will only occur if the envelope penetration increases by 20%.

The GND PROX lights will continue to flash until the alert envelope is exited. Subsequent alerts will only occur if the envelope penetration increases by 20%. <0040>

#### E. Mode 5 - Below Glideslope Alert

Mode 5 provides two levels of alerting during airplane descents below the glideslope on front course ILS approaches.

The first alert level occurs when the aircraft is more than 1.3 dots below the glideslope and is called a "soft" alert. The GPWS lights flash and the GLIDESLOPE aural is generated at approximately one half the volume of other aurals.

The first alert level occurs when the aircraft is more than 1.3 dots below the glideslope and is called a "soft" alert. The GND PROX lights flash and the GLIDESLOPE aural is generated at approximately one half the volume of other aurals. <0040>

The second alert level occurs when the aircraft is below 300 feet radio altitude and is more than 2 dots below the glideslope and is called a "hard" alert. The GPWS lights flash and the GLIDESLOPE aural is generated at the normal aural volume.

The second alert level occurs when the aircraft is below 300 feet radio altitude and is more than 2 dots below the glideslope and is called a "hard" alert. The GND PROX lights flash and the GLIDESLOPE aural is generated at the normal aural volume. <0040>

The GPWS lights will go out once the glideslope deviation is less than 1.3 dots.

The GND PROX lights will go out once the glideslope deviation is less than 1.3 dots.  $_{<0040>}$ 

Mode 5 can be inhibited by pushing either GPWS / G/S light while the aircraft is below 1000 feet radio altitude. Modes 1 through 4 aurals have priority over Mode 5 aurals.

Mode 5 can be inhibited by pushing either PULL UP / GND PROX light while the aircraft is below 2000 feet radio altitude. Modes 1 through 4 aurals have priority over Mode 5 aurals. <0040>

# F. Mode 6 - Callouts

Mode 6 provides different combinations of programmable advisory callouts covering the following:

(1) Transition through DH

Radio altitude transition through the highest DH selected for display on either PFD prompts a minimums—type aural. The function is enabled between 1000 and 10 feet AGL. The landing gear must be down to activate the callouts.

Radio altitude transition through the highest DH selected for display on either PFD prompts a minimums-type aural. The function is enabled between 1000 and 10 feet AGL. Barometric altitude transition through the highest MDA selected for display on either PFD also prompts a minimums-type aural. MDA callout generation is enabled once the corrected altitude exceeds the MDA value by 200 feet. If both DH and MDA have been selected, the callout will be generated based on DH. The landing gear must be down to activate the callouts. <0040>

(2) Altitude Callouts

The altitude callout function generates aurals for descent below predetermined altitudes. Altitude callouts are generated only once and are reset by ascending to 1000 feet, or in the event that a transition from approach mode to take-off mode occurs.

(3) Excessive Bank Angle Alerting <0040>

Excessive bank angle alerting is a function of roll angle with respect to altitude above ground level. Upon penetration of the alert envelope boundaries, the BANK ANGLE, BANK ANGLE aural is generated. The aural is issued once, and only repeated if the roll angle increases by 20%. <0040>



# G. Mode 7 - Windshear Detection and Alerting

Mode 7 monitors for windshear conditions during take-off and final approach between radio altitudes of 10 to 1500 feet.

Windshear cautions and warnings are triggered for tail wind and down draft conditions. Windshear warnings generate a siren, a WINDSHEAR, WINDSHEAR, WINDSHEAR aural and a red WINDSHEAR warning on the primary flight displays (PFDs).

Windshear alerts are triggered for headwind and updraft conditions. Windshear alerts generate an amber WINDSHEAR alert on the PFDs.

Flight director command bars provide escape guidance automatically when a windshear warning occurs or when the TOGA (take-off/go-around) switch(s) on the thrust levers are pressed. Pitch limit indicators (alpha-margin indicators) will appear on both primary flight displays for a windshear warning or alert.

The autopilot is automatically disengaged two seconds after windshear warning (if the autopilot is not already disengaged). During those two seconds, the autopilot will follow the windshear escape guidance.

Windshear warnings take priority over all other aural alerts and warnings, except a stall warning.

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Flight Crew Operating Manual CSP A-013	MASIER



Figure 18–80–1

Flight Crew Operating Manual MASTER CSP A-013
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## NAVIGATION SYSTEMS Ground Proximity Warning System

Vol. 1 18-80-8 REV 56, Jan 31/03



Elight Crow Operating Manual	MASTED
CSP A-013	IVIASTER



# NAVIGATION SYSTEMS Ground Proximity Warning System

**Vol. 1** 18-80-9



Primary Flight Display Pilot's and Copilot's Instrument Panels

#### Pitch Limit Marker (amber) (alpha-margin indicator)

Displayed during windshear warning or alert. Comes on for a minimum of 60 seconds. Displays amount of pitch attitude change that can be made before airplane reaches stall angle of attack.

## Flight Director Command Bars (magenta) Provide escape guidance during a windshear

warning or when TOGA is selected on thrust levers.

## Windshear Message

Flashes (amber) then comes on steady to indicate that the airplane is entering an increasing performance windshear condition.

Flashes (red) then comes on steady to indicate that a severe decreasing performance windshear condition has been encountered. Accompanied by aural warning.





Ground Proximity Warning System – Windshear Detection and Alerting  ${\scriptstyle < MST > }$  Figure 18–80–3

## H. Terrain / Obstacle Awareness Alerting and Display <0040>

The terrain awareness alerting function uses airplane geographical position, aircraft altitude, and a terrain database to predict potential conflicts between the aircraft flight path and the terrain.

The terrain awareness alerting continuously computes terrain clearance envelopes ahead of the aircraft. Two envelopes are computed, one corresponding to a terrain caution alert level and one corresponding to a terrain warning alert level.

Terrain data is displayed on the multifunctional displays by pressing RDR / TERR on the display control panel. The terrain display can be overlaid on the multifunctional display in navaid sector and present position map formats. The terrain display is depicted as variable density dot patterns in green, yellow or red. The density and colour are a function of how close the terrain is relative to airplane altitude. When the conditions for either a terrain awareness caution or warning are detected, the terrain display automatically "pops-up" on both multifunctional displays and the range defaults to 10nm. Terrain more than 2000 feet below the airplane, or within 400 feet (vertical) of the nearest runway elevation is not displayed.

When the airplane penetrates the caution envelope boundary, the GND PROX lights flash and the CAUTION TERRAIN, CAUTION TERRAIN aural is generated. Terrain caution areas are shown in solid yellow on the terrain display.

Flight Crew Operating Manual CSP A-013	MASTER

When the aircraft penetrates the warning envelope boundary, the PULL UP lights flash and the TERRAIN, TERRAIN, PULL UP aural is generated. Terrain warning areas are shown in solid red on the terrain display.

An obstacle database is included within the terrain database. When an obstacle caution threat is detected the GND PROX lights flash and a CAUTION OBSTACLE, CAUTION OBSTACLE aural is generated. Obstacle cautions are shown in solid yellow on the terrain display. When an obstacle warning threat is detected the PULL UP lights flash and an OBSTACLE, OBSTACLE, PULL UP aural is generated. Obstacle warnings are shown in solid red on the terrain display.

#### I. Peaks Display Mode <0040>

canadaır

REGIONAL

Peaks display mode is a customer option as an enhancement to the EGPWS terrain display and is enabled via a program pin on system installation.

Peaks mode allows terrain below the aircraft to be viewed on the terrain display during cruise flight. At altitudes safely above all terrain for the display range chosen, the terrain is displayed, independent of aircraft altitude, emphasizing the highest and lowest elevations to provide increased situational awareness in the event of unplanned decent or enroute deviation and for previewing terrain prior to decent.

Two elevation numbers indicating the highest and lowest terrain currently being displayed are overlaid on the display. The elevation numbers indicate terrain in hundreds of feet above sea level (MSL).

#### J. Terrain Clearance Floor <0040>

Terrain clearance floor is an increasing terrain clearance envelope around the nearest runway directly related to the distance from that runway. Terrain clearance floor alerts are based upon current airplane position, nearest runway centre point position, radio altitude, and a database of hard-surfaced runways whose length is greater than 3500 feet. Terrain clearance floor compliments Mode 4 alerts by covering insufficient terrain clearance even when in a landing configuration.

Penetration of the alert envelope activates the GND PROX lights and generates a TOO LOW TERRAIN aural. The aural will occur once upon initial envelope penetration and one time thereafter for each 20% degradation in altitude. The GND PROX lights remain on until the aircraft exits the alert envelope.

Flight Crew Operating Manual CSP A-013	MASTER



Vol. 1 18-80-11

REV 56, Jan 31/03

#### **Terrain Display Annunciations**

- TERRAIN (cyan) Terrain display has been selected.
- TERRAIN TEST (cyan)- GPWS is in self test.
- TERRAIN NOT AVAIL (white) Terrain has been selected for display but the estimated navigation accuracy is insufficient.
- TERRAIN OFF (white)- Terrain has been selected for display but terrain functions have been manually inhibited.



Multifunction Display - Navaid Sector Mode Pilot's and Copilot's Instrument Panels TERRAIN DISPLAY FAIL (amber) Terrain has been selected for display and the required data is either failed, missing, or invalid. TERRAIN RANGE XXX NM (amber) Terrain range disagrees with display

control panel range.

Ground Proximity Warning System Terrain Display <0040> Figure 18-80-4

Flight Crew Operating Manual CSP A-013	MASTER
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REV 56, Jan 31/03



Status Page

Ground Proximity Warning System Status Page < MST> Figure 18-80-5

Flight Crew Operating Manual CSP A-013	MASTER



# K. System Circuit Breakers

SYSTEM	SUB-SYSTEM	CB NAME	BUS BAR	CB PANEL	CB LOCATION	NOTES
Ground Proximity Warning System	Computer	GND PROX WARN	AC BUS 1	1	A15	

Flight Crew Operating Manual CSP A-013	MASTER
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CSP A-013	MASTER

### 1. WEATHER RADAR SYSTEM

The weather radar system provides the flight crew with X-band color display of radar detectable precipitation and ground mapping along the aircraft's flight path. System range is up to 320 nautical miles and up to 60 degrees on either side of the aircraft's flight path. The weather radar control panel provides control of the following:

- System modes Weather, ground map and hold
- Receiver gain control (±18 dB) and gain calibration
- Antenna azimuth scan angle (either  $\pm 60^{\circ}$  or  $\pm 30^{\circ}$ )
- Antenna elevation control (±15°) in either automatic tilt or manual tilt (0.25° increments)
- Antenna pitch and roll stabilization.

The display control panel is used to select the weather radar format on the multifunctional displays (MFDs). The weather radar data can also be overlaid in navaid sector, present position map and TCAS modes.

Split scan operation enables both pilots to control the radar display on their respective MFDs. Each side will operate independently, except that either pilot can control the sector scan of both displays. In split scan operation, the clockwise sweep of the antenna updates the pilot's display and the counterclockwise sweep updates the copilot"s display. If one side is turned off, the system reverts to single scan operation. <0028>

Elight Crew Operating Manual	MASTED
CSP A-013	





Weather Radar System <MST> Figure 18-90-1

Flight Crew Operating Manual MASTER CSP A-013	
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# NAVIGATION SYSTEMS Weather Radar System

Vol. 1 18-90-3

REV 56, Jan 31/03

## XFR

Used to transfer control of display range to opposite side display control panel. Controlling side range values are displayed in white and non-controlling side values are displayed in yellow.

<0028> Used to transfer control to opposite side radar control panel and display control panel. Controlling side range values are

displayed in white and non-controlling side values are displayed in yellow.

## STAB

Used to deselect radar stabilization by disconnecting attitude reference signal in the event of an attitude system failure.

## TILT

Used to change antenna tilt up or down angle for desired radar scanning. Tilt limits are ±15°.



GAIN

Used to select 30° sector scan instead of the normal 60° sector scan. Display refresh or update rate doubles.



### gain. NORM - Display colors accurately present detected

- rainfall levels. • -1, -2, -3 Positions: Reduces sensitivity to eliminate weaker weather targets.
- +1, +2, +3 Positions: Increases sensitivity to enable crew to differentiate between rainfall levels.

GCS When pressed in during WX mode, ground cluster suppression (GCS) reduces the intensity of ground returns and permits clearer definition of precipitation. Suppression lasts approximately 12 seconds. Any mode or range change cancels ĞCS.

Used to select radar mode of

- OFF Removes power from the transmitter and places radar in standby mode.
- TEST Starts radar self-test. Test pattern displayed on MFD.
- MAP Ground targets are displayed on MFD in cyan, green, yellow or magenta (depending on strength).
- WX Detectable weather displayed in green, yellow, red or magenta (depending on estimated rainfall rate).

Weather Radar System Control Panel <MST> Figure 18-90-2

	Flight Crew Operating Manual CSP A-013	MASTER
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# NAVIGATION SYSTEMS Weather Radar System



2 Arcs displayed (full range and half scale range) when weather radar is superimposed on the following MFD formats:

- · Navaid sector mode,
- VOR map mode
- FMS mode
- Present position map mode (FMS only)
- TCAS mode Arc color changes to white in ground mapping mode.
- PAC (path attenuation correction) alert, yellow arc displayed.
  Arc indicates heavy precipitation and has attenuated radar beam (cut visibility).
  Additional targets may be masked.

Weather Radar System – MFD Indications <MST> Figure 18–90–3

Flight Crew Operating Manual MASTER CSP A-013
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The colors used on the radar display to represent rainfall intensity are as follows:

	RAINFALL RATE	VIDEO INTEGRATED PROCESSOR (VIP) CATEGORIZATIONS			
COLOR	INCHES/HR (MM/HR)	STORM CATEGORY	VIP LEVEL	RAINFALL RATE INCHES/HR (MM/HR)	
MAGENITA	> 2.1 ( > 52 )	EXTREME	6	> 5.0 ( > 125 )	
MAGENTA		INTENSE	5	2.0 – 5.0 (50 – 125)	
RED	0.5 – 2.1 (12 – 52)	VERY STRONG	4	1 – 2 (25 – 50)	
		STRONG	3	0.5 – 1 (12 – 25)	
YELLOW	0.17 – 0.5 (4 – 12)	MODERATE	2	0.1 - 0.5 (2.5 - 12)	
GREEN	0.04 - 0.17 (1 - 4)	WEAK	1	0.01 - 0.1 (0.25 - 2.5)	
BLACK	< 0.04 (< 1 )				

Flight Crew Operating Manual CSP A-013	MASTER





Weather Radar System – MFD Indications <MST> Figure 18–90–4



# A. System Circuit Breakers

SYSTEM	SUB-SYSTEM	CB NAME	BUS BAR	CB PANEL	CB LOCATION	NOTES
Weather Radar	Receiver / Transmitter	WEATHER RDR R/T	DC BUS 1	1	K3	
	Control Panel	WEATHER RDR CONT 1			К4	
		WEATHER RDR CONT 2			K5	<0028>

Flight Crew Operating Manual MASTER CSP A-013
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Flight Crew Operating Manual	MASTER
C3P A-013	